

**INTRODUCTION  
TO  
LINEAR  
ALGEBRA  
Fourth Edition**

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**MANUAL FOR INSTRUCTORS**

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## Problem Set 1.1, page 8

- 1 The combinations give (a) a line in  $\mathbf{R}^3$  (b) a plane in  $\mathbf{R}^3$  (c) all of  $\mathbf{R}^3$ .
- 2  $\mathbf{v} + \mathbf{w} = (2, 3)$  and  $\mathbf{v} - \mathbf{w} = (6, -1)$  will be the diagonals of the parallelogram with  $\mathbf{v}$  and  $\mathbf{w}$  as two sides going out from  $(0, 0)$ .
- 3 This problem gives the diagonals  $\mathbf{v} + \mathbf{w}$  and  $\mathbf{v} - \mathbf{w}$  of the parallelogram and asks for the sides: The opposite of Problem 2. In this example  $\mathbf{v} = (3, 3)$  and  $\mathbf{w} = (2, -2)$ .
- 4  $3\mathbf{v} + \mathbf{w} = (7, 5)$  and  $c\mathbf{v} + d\mathbf{w} = (2c + d, c + 2d)$ .
- 5  $\mathbf{u} + \mathbf{v} = (-2, 3, 1)$  and  $\mathbf{u} + \mathbf{v} + \mathbf{w} = (0, 0, 0)$  and  $2\mathbf{u} + 2\mathbf{v} + \mathbf{w} = (-2, 3, 1)$ . The vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  are in the same plane because a combination gives  $(0, 0, 0)$ . Stated another way:  $\mathbf{u} = -\mathbf{v} - \mathbf{w}$  is in the plane of  $\mathbf{v}$  and  $\mathbf{w}$ .
- 6 The components of every  $c\mathbf{v} + d\mathbf{w}$  add to zero.  $c = 3$  and  $d = 9$  give  $(3, 3, -6)$ .
- 7 The nine combinations  $c(2, 1) + d(0, 1)$  with  $c = 0, 1, 2$  and  $d = 0, 1, 2$  will lie on a lattice. If we took all whole numbers  $c$  and  $d$ , the lattice would lie over the whole plane.
- 8 The other diagonal is  $\mathbf{v} - \mathbf{w}$  (or else  $\mathbf{w} - \mathbf{v}$ ). Adding diagonals gives  $2\mathbf{v}$  (or  $2\mathbf{w}$ ).
- 9 The fourth corner can be  $(4, 4)$  or  $(4, 0)$  or  $(-2, 2)$ . Three possible parallelograms!
- 10  $\mathbf{i} - \mathbf{j} = (1, 1, 0)$  is in the base ( $x$ - $y$  plane).  $\mathbf{i} + \mathbf{j} + \mathbf{k} = (1, 1, 1)$  is the opposite corner from  $(0, 0, 0)$ . Points in the cube have  $0 \leq x \leq 1, 0 \leq y \leq 1, 0 \leq z \leq 1$ .
- 11 Four more corners  $(1, 1, 0), (1, 0, 1), (0, 1, 1), (1, 1, 1)$ . The center point is  $(\frac{1}{2}, \frac{1}{2}, \frac{1}{2})$ . Centers of faces are  $(\frac{1}{2}, \frac{1}{2}, 0), (\frac{1}{2}, \frac{1}{2}, 1)$  and  $(0, \frac{1}{2}, \frac{1}{2}), (1, \frac{1}{2}, \frac{1}{2})$  and  $(\frac{1}{2}, 0, \frac{1}{2}), (\frac{1}{2}, 1, \frac{1}{2})$ .
- 12 A four-dimensional cube has  $2^4 = 16$  corners and  $2 \cdot 4 = 8$  three-dimensional faces and 24 two-dimensional faces and 32 edges in Worked Example 2.4 A.
- 13 Sum = zero vector. Sum = -2:00 vector = 8:00 vector. 2:00 is  $30^\circ$  from horizontal =  $(\cos \frac{\pi}{6}, \sin \frac{\pi}{6}) = (\sqrt{3}/2, 1/2)$ .
- 14 Moving the origin to 6:00 adds  $\mathbf{j} = (0, 1)$  to every vector. So the sum of twelve vectors changes from  $\mathbf{0}$  to  $12\mathbf{j} = (0, 12)$ .
- 15 The point  $\frac{3}{4}\mathbf{v} + \frac{1}{4}\mathbf{w}$  is three-fourths of the way to  $\mathbf{v}$  starting from  $\mathbf{w}$ . The vector  $\frac{1}{4}\mathbf{v} + \frac{1}{4}\mathbf{w}$  is halfway to  $\mathbf{u} = \frac{1}{2}\mathbf{v} + \frac{1}{2}\mathbf{w}$ . The vector  $\mathbf{v} + \mathbf{w}$  is  $2\mathbf{u}$  (the far corner of the parallelogram).
- 16 All combinations with  $c + d = 1$  are on the line that passes through  $\mathbf{v}$  and  $\mathbf{w}$ . The point  $\mathbf{V} = -\mathbf{v} + 2\mathbf{w}$  is on that line but it is beyond  $\mathbf{w}$ .
- 17 All vectors  $c\mathbf{v} + c\mathbf{w}$  are on the line passing through  $(0, 0)$  and  $\mathbf{u} = \frac{1}{2}\mathbf{v} + \frac{1}{2}\mathbf{w}$ . That line continues out beyond  $\mathbf{v} + \mathbf{w}$  and back beyond  $(0, 0)$ . With  $c \geq 0$ , half of this line is removed, leaving a ray that starts at  $(0, 0)$ .
- 18 The combinations  $c\mathbf{v} + d\mathbf{w}$  with  $0 \leq c \leq 1$  and  $0 \leq d \leq 1$  fill the parallelogram with sides  $\mathbf{v}$  and  $\mathbf{w}$ . For example, if  $\mathbf{v} = (1, 0)$  and  $\mathbf{w} = (0, 1)$  then  $c\mathbf{v} + d\mathbf{w}$  fills the unit square.
- 19 With  $c \geq 0$  and  $d \geq 0$  we get the infinite “cone” or “wedge” between  $\mathbf{v}$  and  $\mathbf{w}$ . For example, if  $\mathbf{v} = (1, 0)$  and  $\mathbf{w} = (0, 1)$ , then the cone is the whole quadrant  $x \geq 0, y \geq 0$ . Question: What if  $\mathbf{w} = -\mathbf{v}$ ? The cone opens to a half-space.

- 20 (a)  $\frac{1}{3}\mathbf{u} + \frac{1}{3}\mathbf{v} + \frac{1}{3}\mathbf{w}$  is the center of the triangle between  $\mathbf{u}$ ,  $\mathbf{v}$  and  $\mathbf{w}$ ;  $\frac{1}{2}\mathbf{u} + \frac{1}{2}\mathbf{w}$  lies between  $\mathbf{u}$  and  $\mathbf{w}$  (b) To fill the triangle keep  $c \geq 0$ ,  $d \geq 0$ ,  $e \geq 0$ , and  $c + d + e = 1$ .
- 21 The sum is  $(\mathbf{v} - \mathbf{u}) + (\mathbf{w} - \mathbf{v}) + (\mathbf{u} - \mathbf{w}) = \mathbf{zero\ vector}$ . Those three sides of a triangle are in the same plane!
- 22 The vector  $\frac{1}{2}(\mathbf{u} + \mathbf{v} + \mathbf{w})$  is *outside* the pyramid because  $c + d + e = \frac{1}{2} + \frac{1}{2} + \frac{1}{2} > 1$ .
- 23 All vectors are combinations of  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$  as drawn (not in the same plane). Start by seeing that  $c\mathbf{u} + d\mathbf{v}$  fills a plane, then adding  $e\mathbf{w}$  fills all of  $\mathbf{R}^3$ .
- 24 The combinations of  $\mathbf{u}$  and  $\mathbf{v}$  fill one plane. The combinations of  $\mathbf{v}$  and  $\mathbf{w}$  fill another plane. Those planes meet in a *line*: *only the vectors*  $c\mathbf{v}$  are in both planes.
- 25 (a) For a line, choose  $\mathbf{u} = \mathbf{v} = \mathbf{w} =$  any nonzero vector (b) For a plane, choose  $\mathbf{u}$  and  $\mathbf{v}$  in different directions. A combination like  $\mathbf{w} = \mathbf{u} + \mathbf{v}$  is in the same plane.
- 26 Two equations come from the two components:  $c + 3d = 14$  and  $2c + d = 8$ . The solution is  $c = 2$  and  $d = 4$ . Then  $2(1, 2) + 4(3, 1) = (14, 8)$ .
- 27 The combinations of  $\mathbf{i} = (1, 0, 0)$  and  $\mathbf{i} + \mathbf{j} = (1, 1, 0)$  fill the  $xy$  plane in  $xyz$  space.
- 28 There are 6 unknown numbers  $v_1, v_2, v_3, w_1, w_2, w_3$ . The six equations come from the components of  $\mathbf{v} + \mathbf{w} = (4, 5, 6)$  and  $\mathbf{v} - \mathbf{w} = (2, 5, 8)$ . Add to find  $2\mathbf{v} = (6, 10, 14)$  so  $\mathbf{v} = (3, 5, 7)$  and  $\mathbf{w} = (1, 0, -1)$ .
- 29 Two combinations out of infinitely many that produce  $\mathbf{b} = (0, 1)$  are  $-2\mathbf{u} + \mathbf{v}$  and  $\frac{1}{2}\mathbf{w} - \frac{1}{2}\mathbf{v}$ . **No**, three vectors  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  in the  $x$ - $y$  plane could fail to produce  $\mathbf{b}$  if all three lie on a line that does not contain  $\mathbf{b}$ . **Yes**, if one combination produces  $\mathbf{b}$  then two (and infinitely many) combinations will produce  $\mathbf{b}$ . This is true even if  $\mathbf{u} = \mathbf{0}$ ; the combinations can have different  $c\mathbf{u}$ .
- 30 The combinations of  $\mathbf{v}$  and  $\mathbf{w}$  fill the plane *unless*  $\mathbf{v}$  and  $\mathbf{w}$  lie on the same line through  $(0, 0)$ . Four vectors whose combinations fill 4-dimensional space: one example is the “standard basis”  $(1, 0, 0, 0)$ ,  $(0, 1, 0, 0)$ ,  $(0, 0, 1, 0)$ , and  $(0, 0, 0, 1)$ .
- 31 The equations  $c\mathbf{u} + d\mathbf{v} + e\mathbf{w} = \mathbf{b}$  are

$$\begin{array}{rcl} 2c - d & = & 1 \\ -c + 2d - e & = & 0 \\ -d + 2e & = & 0 \end{array} \quad \begin{array}{l} \text{So } d = 2e \\ \text{then } c = 3e \\ \text{then } 4e = 1 \end{array} \quad \begin{array}{l} c = 3/4 \\ d = 2/4 \\ e = 1/4 \end{array}$$

## Problem Set 1.2, page 19

- 1  $\mathbf{u} \cdot \mathbf{v} = -1.8 + 3.2 = 1.4$ ,  $\mathbf{u} \cdot \mathbf{w} = -4.8 + 4.8 = 0$ ,  $\mathbf{v} \cdot \mathbf{w} = 24 + 24 = 48 = \mathbf{w} \cdot \mathbf{v}$ .
- 2  $\|\mathbf{u}\| = 1$  and  $\|\mathbf{v}\| = 5$  and  $\|\mathbf{w}\| = 10$ . Then  $1.4 < (1)(5)$  and  $48 < (5)(10)$ , confirming the Schwarz inequality.
- 3 Unit vectors  $\mathbf{v}/\|\mathbf{v}\| = (\frac{3}{5}, \frac{4}{5}) = (.6, .8)$  and  $\mathbf{w}/\|\mathbf{w}\| = (\frac{4}{5}, \frac{3}{5}) = (.8, .6)$ . The cosine of  $\theta$  is  $\frac{\mathbf{v}}{\|\mathbf{v}\|} \cdot \frac{\mathbf{w}}{\|\mathbf{w}\|} = \frac{24}{25}$ . The vectors  $\mathbf{w}, \mathbf{u}, -\mathbf{w}$  make  $0^\circ, 90^\circ, 180^\circ$  angles with  $\mathbf{w}$ .
- 4 (a)  $\mathbf{v} \cdot (-\mathbf{v}) = -1$  (b)  $(\mathbf{v} + \mathbf{w}) \cdot (\mathbf{v} - \mathbf{w}) = \mathbf{v} \cdot \mathbf{v} + \mathbf{w} \cdot \mathbf{v} - \mathbf{v} \cdot \mathbf{w} - \mathbf{w} \cdot \mathbf{w} = 1 + (\quad) - (\quad) - 1 = 0$  so  $\theta = 90^\circ$  (notice  $\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v}$ ) (c)  $(\mathbf{v} - 2\mathbf{w}) \cdot (\mathbf{v} + 2\mathbf{w}) = \mathbf{v} \cdot \mathbf{v} - 4\mathbf{w} \cdot \mathbf{w} = 1 - 4 = -3$ .

- 5  $\mathbf{u}_1 = \mathbf{v}/\|\mathbf{v}\| = (3, 1)/\sqrt{10}$  and  $\mathbf{u}_2 = \mathbf{w}/\|\mathbf{w}\| = (2, 1, 2)/3$ .  $\mathbf{U}_1 = (1, -3)/\sqrt{10}$  is perpendicular to  $\mathbf{u}_1$  (and so is  $(-1, 3)/\sqrt{10}$ ).  $\mathbf{U}_2$  could be  $(1, -2, 0)/\sqrt{5}$ : There is a whole plane of vectors perpendicular to  $\mathbf{u}_2$ , and a whole circle of unit vectors in that plane.
- 6 All vectors  $\mathbf{w} = (c, 2c)$  are perpendicular to  $\mathbf{v}$ . All vectors  $(x, y, z)$  with  $x + y + z = 0$  lie on a *plane*. All vectors perpendicular to  $(1, 1, 1)$  and  $(1, 2, 3)$  lie on a *line*.
- 7 (a)  $\cos \theta = \mathbf{v} \cdot \mathbf{w}/\|\mathbf{v}\|\|\mathbf{w}\| = 1/(2)(1)$  so  $\theta = 60^\circ$  or  $\pi/3$  radians (b)  $\cos \theta = 0$  so  $\theta = 90^\circ$  or  $\pi/2$  radians (c)  $\cos \theta = 2/(2)(2) = 1/2$  so  $\theta = 60^\circ$  or  $\pi/3$  (d)  $\cos \theta = -1/\sqrt{2}$  so  $\theta = 135^\circ$  or  $3\pi/4$ .
- 8 (a) False:  $\mathbf{v}$  and  $\mathbf{w}$  are any vectors in the plane perpendicular to  $\mathbf{u}$  (b) True:  $\mathbf{u} \cdot (\mathbf{v} + 2\mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + 2\mathbf{u} \cdot \mathbf{w} = 0$  (c) True,  $\|\mathbf{u} - \mathbf{v}\|^2 = (\mathbf{u} - \mathbf{v}) \cdot (\mathbf{u} - \mathbf{v})$  splits into  $\mathbf{u} \cdot \mathbf{u} + \mathbf{v} \cdot \mathbf{v} = 2$  when  $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u} = 0$ .
- 9 If  $v_2 w_2 / v_1 w_1 = -1$  then  $v_2 w_2 = -v_1 w_1$  or  $v_1 w_1 + v_2 w_2 = \mathbf{v} \cdot \mathbf{w} = 0$ : perpendicular!
- 10 Slopes  $2/1$  and  $-1/2$  multiply to give  $-1$ : then  $\mathbf{v} \cdot \mathbf{w} = 0$  and the vectors (the directions) are perpendicular.
- 11  $\mathbf{v} \cdot \mathbf{w} < 0$  means angle  $> 90^\circ$ ; these  $\mathbf{w}$ 's fill half of 3-dimensional space.
- 12  $(1, 1)$  perpendicular to  $(1, 5) - c(1, 1)$  if  $6 - 2c = 0$  or  $c = 3$ ;  $\mathbf{v} \cdot (\mathbf{w} - c\mathbf{v}) = 0$  if  $c = \mathbf{v} \cdot \mathbf{w} / \mathbf{v} \cdot \mathbf{v}$ . Subtracting  $c\mathbf{v}$  is the key to perpendicular vectors.
- 13 The plane perpendicular to  $(1, 0, 1)$  contains all vectors  $(c, d, -c)$ . In that plane,  $\mathbf{v} = (1, 0, -1)$  and  $\mathbf{w} = (0, 1, 0)$  are perpendicular.
- 14 One possibility among many:  $\mathbf{u} = (1, -1, 0, 0)$ ,  $\mathbf{v} = (0, 0, 1, -1)$ ,  $\mathbf{w} = (1, 1, -1, -1)$  and  $(1, 1, 1, 1)$  are perpendicular to each other. "We can rotate those  $\mathbf{u}, \mathbf{v}, \mathbf{w}$  in their 3D hyperplane."
- 15  $\frac{1}{2}(x + y) = (2 + 8)/2 = 5$ ;  $\cos \theta = 2\sqrt{16}/\sqrt{10}\sqrt{10} = 8/10$ .
- 16  $\|\mathbf{v}\|^2 = 1 + 1 + \dots + 1 = 9$  so  $\|\mathbf{v}\| = 3$ ;  $\mathbf{u} = \mathbf{v}/3 = (\frac{1}{3}, \dots, \frac{1}{3})$  is a unit vector in 9D;  $\mathbf{w} = (1, -1, 0, \dots, 0)/\sqrt{2}$  is a unit vector in the 8D hyperplane perpendicular to  $\mathbf{v}$ .
- 17  $\cos \alpha = 1/\sqrt{2}$ ,  $\cos \beta = 0$ ,  $\cos \gamma = -1/\sqrt{2}$ . For any vector  $\mathbf{v}$ ,  $\cos^2 \alpha + \cos^2 \beta + \cos^2 \gamma = (v_1^2 + v_2^2 + v_3^2)/\|\mathbf{v}\|^2 = 1$ .
- 18  $\|\mathbf{v}\|^2 = 4^2 + 2^2 = 20$  and  $\|\mathbf{w}\|^2 = (-1)^2 + 2^2 = 5$ . Pythagoras is  $\|(3, 4)\|^2 = 25 = 20 + 5$ .
- 19 Start from the rules (1), (2), (3) for  $\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v}$  and  $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w})$  and  $(c\mathbf{v}) \cdot \mathbf{w}$ . Use rule (2) for  $(\mathbf{v} + \mathbf{w}) \cdot (\mathbf{v} + \mathbf{w}) = (\mathbf{v} + \mathbf{w}) \cdot \mathbf{v} + (\mathbf{v} + \mathbf{w}) \cdot \mathbf{w}$ . By rule (1) this is  $\mathbf{v} \cdot (\mathbf{v} + \mathbf{w}) + \mathbf{w} \cdot (\mathbf{v} + \mathbf{w})$ . Rule (2) again gives  $\mathbf{v} \cdot \mathbf{v} + \mathbf{v} \cdot \mathbf{w} + \mathbf{w} \cdot \mathbf{v} + \mathbf{w} \cdot \mathbf{w} = \mathbf{v} \cdot \mathbf{v} + 2\mathbf{v} \cdot \mathbf{w} + \mathbf{w} \cdot \mathbf{w}$ . Notice  $\mathbf{v} \cdot \mathbf{w} = \mathbf{w} \cdot \mathbf{v}$ ! The main point is to be free to open up parentheses.
- 20 We know that  $(\mathbf{v} - \mathbf{w}) \cdot (\mathbf{v} - \mathbf{w}) = \mathbf{v} \cdot \mathbf{v} - 2\mathbf{v} \cdot \mathbf{w} + \mathbf{w} \cdot \mathbf{w}$ . The Law of Cosines writes  $\|\mathbf{v}\|\|\mathbf{w}\|\cos \theta$  for  $\mathbf{v} \cdot \mathbf{w}$ . When  $\theta < 90^\circ$  this  $\mathbf{v} \cdot \mathbf{w}$  is positive, so in this case  $\mathbf{v} \cdot \mathbf{v} + \mathbf{w} \cdot \mathbf{w}$  is larger than  $\|\mathbf{v} - \mathbf{w}\|^2$ .
- 21  $2\mathbf{v} \cdot \mathbf{w} \leq 2\|\mathbf{v}\|\|\mathbf{w}\|$  leads to  $\|\mathbf{v} + \mathbf{w}\|^2 = \mathbf{v} \cdot \mathbf{v} + 2\mathbf{v} \cdot \mathbf{w} + \mathbf{w} \cdot \mathbf{w} \leq \|\mathbf{v}\|^2 + 2\|\mathbf{v}\|\|\mathbf{w}\| + \|\mathbf{w}\|^2$ . This is  $(\|\mathbf{v}\| + \|\mathbf{w}\|)^2$ . Taking square roots gives  $\|\mathbf{v} + \mathbf{w}\| \leq \|\mathbf{v}\| + \|\mathbf{w}\|$ .
- 22  $v_1^2 w_1^2 + 2v_1 w_1 v_2 w_2 + v_2^2 w_2^2 \leq v_1^2 w_1^2 + v_1^2 w_2^2 + v_2^2 w_1^2 + v_2^2 w_2^2$  is true (cancel 4 terms) because the difference is  $v_1^2 w_2^2 + v_2^2 w_1^2 - 2v_1 w_1 v_2 w_2$  which is  $(v_1 w_2 - v_2 w_1)^2 \geq 0$ .

- 23**  $\cos \beta = w_1/\|\mathbf{w}\|$  and  $\sin \beta = w_2/\|\mathbf{w}\|$ . Then  $\cos(\beta - \alpha) = \cos \beta \cos \alpha + \sin \beta \sin \alpha = v_1 w_1/\|\mathbf{v}\|\|\mathbf{w}\| + v_2 w_2/\|\mathbf{v}\|\|\mathbf{w}\| = \mathbf{v} \cdot \mathbf{w}/\|\mathbf{v}\|\|\mathbf{w}\|$ . This is  $\cos \theta$  because  $\beta - \alpha = \theta$ .
- 24** Example 6 gives  $|u_1|U_1| \leq \frac{1}{2}(u_1^2 + U_1^2)$  and  $|u_2|U_2| \leq \frac{1}{2}(u_2^2 + U_2^2)$ . The whole line becomes  $.96 \leq (.6)(.8) + (.8)(.6) \leq \frac{1}{2}(.6^2 + .8^2) + \frac{1}{2}(.8^2 + .6^2) = 1$ . True:  $.96 < 1$ .
- 25** The cosine of  $\theta$  is  $x/\sqrt{x^2 + y^2}$ , near side over hypotenuse. Then  $|\cos \theta|^2$  is not greater than 1:  $x^2/(x^2 + y^2) \leq 1$ .
- 26** The vectors  $\mathbf{w} = (x, y)$  with  $(1, 2) \cdot \mathbf{w} = x + 2y = 5$  lie on a line in the  $xy$  plane. The shortest  $\mathbf{w}$  on that line is  $(1, 2)$ . (The Schwarz inequality  $\|\mathbf{w}\| \geq \mathbf{v} \cdot \mathbf{w}/\|\mathbf{v}\| = \sqrt{5}$  is an equality when  $\cos \theta = 1$  and  $\mathbf{w} = (1, 2)$  and  $\|\mathbf{w}\| = \sqrt{5}$ .)
- 27** The length  $\|\mathbf{v} - \mathbf{w}\|$  is between 2 and 8 (triangle inequality when  $\|\mathbf{v}\| = 5$  and  $\|\mathbf{w}\| = 3$ ). The dot product  $\mathbf{v} \cdot \mathbf{w}$  is between  $-15$  and  $15$  by the Schwarz inequality.
- 28** Three vectors in the plane could make angles greater than  $90^\circ$  with each other: for example  $(1, 0), (-1, 4), (-1, -4)$ . Four vectors could *not* do this ( $360^\circ$  total angle). How many can do this in  $\mathbf{R}^3$  or  $\mathbf{R}^n$ ? Ben Harris and Greg Marks showed me that the answer is  $n + 1$ . The vectors from the center of a regular simplex in  $\mathbf{R}^n$  to its  $n + 1$  vertices all have negative dot products. If  $n + 2$  vectors in  $\mathbf{R}^n$  had negative dot products, project them onto the plane orthogonal to the last one. Now you have  $n + 1$  vectors in  $\mathbf{R}^{n-1}$  with negative dot products. Keep going to 4 vectors in  $\mathbf{R}^2$ : no way!
- 29** For a specific example, pick  $\mathbf{v} = (1, 2, -3)$  and then  $\mathbf{w} = (-3, 1, 2)$ . In this example  $\cos \theta = \mathbf{v} \cdot \mathbf{w}/\|\mathbf{v}\|\|\mathbf{w}\| = -7/\sqrt{14}\sqrt{14} = -1/2$  and  $\theta = 120^\circ$ . This always happens when  $x + y + z = 0$ :

$$\mathbf{v} \cdot \mathbf{w} = xz + xy + yz = \frac{1}{2}(x + y + z)^2 - \frac{1}{2}(x^2 + y^2 + z^2)$$

This is the same as  $\mathbf{v} \cdot \mathbf{w} = 0 - \frac{1}{2}\|\mathbf{v}\|\|\mathbf{w}\|$ . Then  $\cos \theta = \frac{1}{2}$ .

- 30** Wikipedia gives this proof of geometric mean  $G = \sqrt[3]{xyz} \leq$  arithmetic mean  $A = (x + y + z)/3$ . First there is equality in case  $x = y = z$ . Otherwise  $A$  is somewhere between the three positive numbers, say for example  $z < A < y$ .

Use the known inequality  $g \leq a$  for the *two* positive numbers  $x$  and  $y + z - A$ . Their mean  $a = \frac{1}{2}(x + y + z - A)$  is  $\frac{1}{2}(3A - A) =$  same as  $A$ ! So  $a \geq g$  says that  $A^3 \geq g^2 A = x(y + z - A)A$ . But  $(y + z - A)A = (y - A)(A - z) + yz > yz$ . Substitute to find  $A^3 > xyz = G^3$  as we wanted to prove. Not easy!

There are many proofs of  $G = (x_1 x_2 \cdots x_n)^{1/n} \leq A = (x_1 + x_2 + \cdots + x_n)/n$ . In calculus you are maximizing  $G$  on the plane  $x_1 + x_2 + \cdots + x_n = n$ . The maximum occurs when all  $x$ 's are equal.

- 31** The columns of the 4 by 4 "Hadamard matrix" (times  $\frac{1}{2}$ ) are perpendicular unit vectors:

$$\frac{1}{2}H = \frac{1}{2} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & -1 & 1 \end{bmatrix}.$$

- 32** The commands  $V = \text{randn}(3, 30)$ ;  $D = \text{sqrt}(\text{diag}(V' * V))$ ;  $U = V \setminus D$ ; will give 30 random unit vectors in the columns of  $U$ . Then  $u' * U$  is a row matrix of 30 dot products whose average absolute value may be close to  $2/\pi$ .

### Problem Set 1.3, page 29

- 1  $2s_1 + 3s_2 + 4s_3 = (2, 5, 9)$ . The same vector  $\mathbf{b}$  comes from  $S$  times  $\mathbf{x} = (2, 3, 4)$ :

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} (\text{row 1}) \cdot \mathbf{x} \\ (\text{row 2}) \cdot \mathbf{x} \\ (\text{row 3}) \cdot \mathbf{x} \end{bmatrix} = \begin{bmatrix} 2 \\ 5 \\ 9 \end{bmatrix}.$$

- 2 The solutions are  $y_1 = 1, y_2 = 0, y_3 = 0$  (right side = column 1) and  $y_1 = 1, y_2 = 3, y_3 = 5$ . That second example illustrates that the first  $n$  odd numbers add to  $n^2$ .

$$\begin{array}{rcl} y_1 & = & B_1 \\ y_1 + y_2 & = & B_2 \\ y_1 + y_2 + y_3 & = & B_3 \end{array} \quad \text{gives} \quad \begin{array}{rcl} y_1 & = & B_1 \\ y_2 & = & -B_1 + B_2 \\ y_3 & = & -B_2 + B_3 \end{array} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ B_3 \end{bmatrix}$$

The inverse of  $S = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$  is  $A = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$ : independent columns in  $A$  and  $S$ !

- 4 The combination  $0\mathbf{w}_1 + 0\mathbf{w}_2 + 0\mathbf{w}_3$  always gives the zero vector, but this problem looks for other *zero* combinations (then the vectors are *dependent*, they lie in a plane):  $\mathbf{w}_2 = (\mathbf{w}_1 + \mathbf{w}_3)/2$  so one combination that gives zero is  $\frac{1}{2}\mathbf{w}_1 - \mathbf{w}_2 + \frac{1}{2}\mathbf{w}_3$ .

- 5 The rows of the 3 by 3 matrix in Problem 4 must also be *dependent*:  $\mathbf{r}_2 = \frac{1}{2}(\mathbf{r}_1 + \mathbf{r}_3)$ . The column and row combinations that produce  $\mathbf{0}$  are the same: this is unusual.

$$\begin{array}{lcl} 6 \quad c = 3 & \begin{bmatrix} 1 & 3 & 5 \\ 1 & 2 & 4 \\ 1 & 1 & 3 \end{bmatrix} & \text{has column 3} = 2(\text{column 1}) + \text{column 2} \\ c = -1 & \begin{bmatrix} 1 & 0 & -1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} & \text{has column 3} = -\text{column 1} + \text{column 2} \\ c = 0 & \begin{bmatrix} 0 & 0 & 0 \\ 2 & 1 & 5 \\ 3 & 3 & 6 \end{bmatrix} & \text{has column 3} = 3(\text{column 1}) - \text{column 2} \end{array}$$

- 7 All three rows are perpendicular to the solution  $\mathbf{x}$  (the three equations  $\mathbf{r}_1 \cdot \mathbf{x} = 0$  and  $\mathbf{r}_2 \cdot \mathbf{x} = 0$  and  $\mathbf{r}_3 \cdot \mathbf{x} = 0$  tell us this). Then the whole plane of the rows is perpendicular to  $\mathbf{x}$  (the plane is also perpendicular to all multiples  $c\mathbf{x}$ ).

$$\begin{array}{rcl} x_1 - 0 & = & b_1 \\ x_2 - x_1 & = & b_2 \\ x_3 - x_2 & = & b_3 \\ x_4 - x_3 & = & b_4 \end{array} \quad \begin{array}{rcl} x_1 & = & b_1 \\ x_2 & = & b_1 + b_2 \\ x_3 & = & b_1 + b_2 + b_3 \\ x_4 & = & b_1 + b_2 + b_3 + b_4 \end{array} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} = A^{-1}\mathbf{b}$$

- 9 The cyclic difference matrix  $C$  has a line of solutions (in 4 dimensions) to  $C\mathbf{x} = \mathbf{0}$ :

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{when } \mathbf{x} = \begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix} = \text{any constant vector.}$$

$$\begin{array}{rcl}
 z_2 - z_1 = b_1 & z_1 = -b_1 - b_2 - b_3 & \\
 10 \quad z_3 - z_2 = b_2 & z_2 = -b_2 - b_3 & \\
 0 - z_3 = b_3 & z_3 = -b_3 &
 \end{array}
 = \begin{bmatrix} -1 & -1 & -1 \\ 0 & -1 & -1 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = \Delta^{-1} \mathbf{b}$$

11 The forward differences of the squares are  $(t+1)^2 - t^2 = t^2 + 2t + 1 - t^2 = 2t + 1$ . Differences of the  $n$ th power are  $(t+1)^n - t^n = t^n - t^n + nt^{n-1} + \dots$ . The leading term is the derivative  $nt^{n-1}$ . The binomial theorem gives all the terms of  $(t+1)^n$ .

12 Centered difference matrices of *even* size seem to be invertible. Look at eqns. 1 and 4:

$$\begin{bmatrix} 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix} \quad \begin{array}{l} \text{First} \\ \text{solve} \\ x_2 = b_1 \\ -x_3 = b_4 \end{array} \quad \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -b_2 - b_4 \\ b_1 \\ -b_4 \\ b_1 + b_3 \end{bmatrix}$$

13 *Odd size*: The five centered difference equations lead to  $b_1 + b_3 + b_5 = 0$ .

$$\begin{array}{rcl}
 x_2 & = & b_1 \\
 x_3 - x_1 & = & b_2 \\
 x_4 - x_2 & = & b_3 \\
 x_5 - x_3 & = & b_4 \\
 -x_4 & = & b_5
 \end{array}
 \quad \begin{array}{l} \text{Add equations 1, 3, 5} \\ \text{The left side of the sum is zero} \\ \text{The right side is } b_1 + b_3 + b_5 \\ \text{There cannot be a solution unless } b_1 + b_3 + b_5 = 0. \end{array}$$

14 An example is  $(a, b) = (3, 6)$  and  $(c, d) = (1, 2)$ . The ratios  $a/c$  and  $b/d$  are equal. Then  $ad = bc$ . Then (when you divide by  $bd$ ) the ratios  $a/b$  and  $c/d$  are equal!

## Problem Set 2.1, page 40

- The columns are  $\mathbf{i} = (1, 0, 0)$  and  $\mathbf{j} = (0, 1, 0)$  and  $\mathbf{k} = (0, 0, 1)$  and  $\mathbf{b} = (2, 3, 4) = 2\mathbf{i} + 3\mathbf{j} + 4\mathbf{k}$ .
- The planes are the same:  $2x = 4$  is  $x = 2$ ,  $3y = 9$  is  $y = 3$ , and  $4z = 16$  is  $z = 4$ . The solution is the same point  $\mathbf{X} = \mathbf{x}$ . The columns are changed; but same combination.
- The solution is not changed! The second plane and row 2 of the matrix and all columns of the matrix (vectors in the column picture) are changed.
- If  $z = 2$  then  $x + y = 0$  and  $x - y = z$  give the point  $(1, -1, 2)$ . If  $z = 0$  then  $x + y = 6$  and  $x - y = 4$  produce  $(5, 1, 0)$ . Halfway between those is  $(3, 0, 1)$ .
- If  $x, y, z$  satisfy the first two equations they also satisfy the third equation. The line  $\mathbf{L}$  of solutions contains  $\mathbf{v} = (1, 1, 0)$  and  $\mathbf{w} = (\frac{1}{2}, 1, \frac{1}{2})$  and  $\mathbf{u} = \frac{1}{2}\mathbf{v} + \frac{1}{2}\mathbf{w}$  and all combinations  $c\mathbf{v} + d\mathbf{w}$  with  $c + d = 1$ .
- Equation 1 + equation 2 - equation 3 is now  $0 = -4$ . Line misses plane; *no solution*.
- Column 3 = Column 1 makes the matrix singular. Solutions  $(x, y, z) = (1, 1, 0)$  or  $(0, 1, 1)$  and you can add any multiple of  $(-1, 0, 1)$ ;  $\mathbf{b} = (4, 6, c)$  needs  $c = 10$  for solvability (then  $\mathbf{b}$  lies in the plane of the columns).
- Four planes in 4-dimensional space normally meet at a *point*. The solution to  $A\mathbf{x} = (3, 3, 3, 2)$  is  $\mathbf{x} = (0, 0, 1, 2)$  if  $A$  has columns  $(1, 0, 0, 0)$ ,  $(1, 1, 0, 0)$ ,  $(1, 1, 1, 0)$ ,  $(1, 1, 1, 1)$ . The equations are  $x + y + z + t = 3$ ,  $y + z + t = 3$ ,  $z + t = 3$ ,  $t = 2$ .
- (a)  $A\mathbf{x} = (18, 5, 0)$  and (b)  $A\mathbf{x} = (3, 4, 5, 5)$ .

- 10** Multiplying as linear combinations of the columns gives the same  $A\mathbf{x}$ . By rows or by columns: **9** separate multiplications for 3 by 3.
- 11**  $A\mathbf{x}$  equals (14, 22) and (0, 0) and (9, 7).
- 12**  $A\mathbf{x}$  equals (z, y, x) and (0, 0, 0) and (3, 3, 6).
- 13** (a)  $\mathbf{x}$  has  $n$  components and  $A\mathbf{x}$  has  $m$  components (b) Planes from each equation in  $A\mathbf{x} = \mathbf{b}$  are in  $n$ -dimensional space, but the columns are in  $m$ -dimensional space.
- 14**  $2x + 3y + z + 5t = 8$  is  $A\mathbf{x} = \mathbf{b}$  with the 1 by 4 matrix  $A = [2 \ 3 \ 1 \ 5]$ . The solutions  $\mathbf{x}$  fill a 3D “plane” in 4 dimensions. It could be called a *hyperplane*.
- 15** (a)  $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  (b)  $P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$
- 16**  $90^\circ$  rotation from  $R = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ ,  $180^\circ$  rotation from  $R^2 = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} = -I$ .
- 17**  $P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$  produces (y, z, x) and  $Q = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$  recovers (x, y, z).  $Q$  is the inverse of  $P$ .
- 18**  $E = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$  and  $E = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$  subtract the first component from the second.
- 19**  $E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$  and  $E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ ,  $E\mathbf{v} = (3, 4, 8)$  and  $E^{-1}E\mathbf{v}$  recovers (3, 4, 5).
- 20**  $P_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  projects onto the  $x$ -axis and  $P_2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$  projects onto the  $y$ -axis.  $\mathbf{v} = \begin{bmatrix} 5 \\ 7 \end{bmatrix}$  has  $P_1\mathbf{v} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$  and  $P_2P_1\mathbf{v} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .
- 21**  $R = \frac{1}{2} \begin{bmatrix} \sqrt{2} & -\sqrt{2} \\ \sqrt{2} & \sqrt{2} \end{bmatrix}$  rotates all vectors by  $45^\circ$ . The columns of  $R$  are the results from rotating (1, 0) and (0, 1)!
- 22** The dot product  $A\mathbf{x} = [1 \ 4 \ 5] \begin{bmatrix} x \\ y \\ z \end{bmatrix} = (1 \text{ by } 3)(3 \text{ by } 1)$  is zero for points (x, y, z) on a plane in three dimensions. The columns of  $A$  are one-dimensional vectors.
- 23**  $A = [1 \ 2 \ ; \ 3 \ 4]$  and  $\mathbf{x} = [5 \ -2]'$  and  $\mathbf{b} = [1 \ 7]'$ .  $\mathbf{r} = \mathbf{b} - A * \mathbf{x}$  prints as zero.
- 24**  $A * \mathbf{v} = [3 \ 4 \ 5]'$  and  $\mathbf{v}' * \mathbf{v} = 50$ . But  $\mathbf{v} * A$  gives an error message from 3 by 1 times 3 by 3.
- 25**  $\mathbf{ones}(4, 4) * \mathbf{ones}(4, 1) = [4 \ 4 \ 4 \ 4]'$ ;  $B * \mathbf{w} = [10 \ 10 \ 10 \ 10]'$ .
- 26** The row picture has two lines meeting at the solution (4, 2). The column picture will have  $4(1, 1) + 2(-2, 1) = 4(\text{column } 1) + 2(\text{column } 2) = \text{right side } (0, 6)$ .
- 27** The row picture shows **2 planes in 3-dimensional space**. The column picture is in **2-dimensional space**. The solutions normally lie on a *line*.



- 28** The row picture shows four *lines* in the 2D plane. The column picture is in *four*-dimensional space. No solution unless the right side is a combination of *the two columns*.
- 29**  $u_2 = \begin{bmatrix} .7 \\ .3 \end{bmatrix}$  and  $u_3 = \begin{bmatrix} .65 \\ .35 \end{bmatrix}$ . The components add to 1. They are always positive.  $u_7, v_7, w_7$  are all close to  $(.6, .4)$ . Their components still add to 1.
- 30**  $\begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix} \begin{bmatrix} .6 \\ .4 \end{bmatrix} = \begin{bmatrix} .6 \\ .4 \end{bmatrix} = \text{steady state } s$ . No change when multiplied by  $\begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix}$ .
- 31**  $M = \begin{bmatrix} 8 & 3 & 4 \\ 1 & 5 & 9 \\ 6 & 7 & 2 \end{bmatrix} = \begin{bmatrix} 5+u & 5-u+v & 5-v \\ 5-u-v & 5 & 5+u+v \\ 5+v & 5+u-v & 5-u \end{bmatrix}$ ;  $M_3(1, 1, 1) = (15, 15, 15)$ ;  $M_4(1, 1, 1, 1) = (34, 34, 34, 34)$  because  $1 + 2 + \cdots + 16 = 136$  which is  $4(34)$ .
- 32**  $A$  is singular when its third column  $w$  is a combination  $cu + dv$  of the first columns. A typical column picture has  $b$  outside the plane of  $u, v, w$ . A typical row picture has the intersection line of two planes parallel to the third plane. *Then no solution.*
- 33**  $w = (5, 7)$  is  $5u + 7v$ . Then  $Aw$  equals 5 times  $Au$  plus 7 times  $Av$ .
- 34**  $\begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$  has the solution  $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 4 \\ 7 \\ 8 \\ 6 \end{bmatrix}$ .
- 35**  $x = (1, \dots, 1)$  gives  $Sx = \text{sum of each row} = 1 + \cdots + 9 = 45$  for Sudoku matrices. 6 row orders  $(1, 2, 3), (1, 3, 2), (2, 1, 3), (2, 3, 1), (3, 1, 2), (3, 2, 1)$  are in Section 2.7. The same 6 permutations of *blocks* of rows produce Sudoku matrices, so  $6^4 = 1296$  orders of the 9 rows all stay Sudoku. (And also 1296 permutations of the 9 columns.)

## Problem Set 2.2, page 51

- Multiply by  $\ell_{21} = \frac{10}{2} = 5$  and subtract to find  $2x + 3y = 14$  and  $-6y = 6$ . The pivots to circle are 2 and  $-6$ .
- $-6y = 6$  gives  $y = -1$ . Then  $2x + 3y = 1$  gives  $x = 2$ . Multiplying the right side  $(1, 11)$  by 4 will multiply the solution by 4 to give the new solution  $(x, y) = (8, -4)$ .
- Subtract  $-\frac{1}{2}$  (or add  $\frac{1}{2}$ ) times equation 1. The new second equation is  $3y = 3$ . Then  $y = 1$  and  $x = 5$ . If the right side changes sign, so does the solution:  $(x, y) = (-5, -1)$ .
- Subtract  $\ell = \frac{c}{a}$  times equation 1. The new second pivot multiplying  $y$  is  $d - (cb/a)$  or  $(ad - bc)/a$ . Then  $y = (ag - cf)/(ad - bc)$ .
- $6x + 4y$  is 2 times  $3x + 2y$ . There is no solution unless the right side is  $2 \cdot 10 = 20$ . Then all the points on the line  $3x + 2y = 10$  are solutions, including  $(0, 5)$  and  $(4, -1)$ . (The two lines in the row picture are the same line, containing all solutions).
- Singular system if  $b = 4$ , because  $4x + 8y$  is 2 times  $2x + 4y$ . Then  $g = 32$  makes the lines become the *same*: infinitely many solutions like  $(8, 0)$  and  $(0, 4)$ .
- If  $a = 2$  elimination must fail (two parallel lines in the row picture). The equations have no solution. With  $a = 0$ , elimination will stop for a row exchange. Then  $3y = -3$  gives  $y = -1$  and  $4x + 6y = 6$  gives  $x = 3$ .

- 8 If  $k = 3$  elimination must fail: no solution. If  $k = -3$ , elimination gives  $0 = 0$  in equation 2: infinitely many solutions. If  $k = 0$  a row exchange is needed: one solution.
- 9 On the left side,  $6x - 4y$  is 2 times  $(3x - 2y)$ . Therefore we need  $b_2 = 2b_1$  on the right side. Then there will be infinitely many solutions (two parallel lines become one single line).
- 10 The equation  $y = 1$  comes from elimination (subtract  $x + y = 5$  from  $x + 2y = 6$ ). Then  $x = 4$  and  $5x - 4y = c = 16$ .
- 11 (a) Another solution is  $\frac{1}{2}(x + X, y + Y, z + Z)$ . (b) If 25 planes meet at two points, they meet along the whole line through those two points.
- 12 Elimination leads to an upper triangular system; then comes back substitution.
- $$\begin{array}{rcl} 2x + 3y + z = 8 & & x = 2 \\ y + 3z = 4 & \text{gives} & y = 1 \\ 8z = 8 & & z = 1 \end{array}$$
- If a zero is at the start of row 2 or 3, that avoids a row operation.
- 13
- $$\begin{array}{rcl} 2x - 3y & = & 3 \\ 4x - 5y + z = 7 & \text{gives} & y + z = 1 \\ 2x - y - 3z = 5 & & 2y + 3z = 2 \end{array}$$
- $$\begin{array}{rcl} 2x - 3y & = & 3 \\ y + z & = & 1 \\ y + z & = & 1 \\ -5z & = & 0 \end{array}$$
- Subtract  $2 \times$  row 1 from row 2, subtract  $1 \times$  row 1 from row 3, subtract  $2 \times$  row 2 from row 3
- 14 Subtract 2 times row 1 from row 2 to reach  $(d - 10)y - z = 2$ . Equation (3) is  $y - z = 3$ . If  $d = 10$  exchange rows 2 and 3. If  $d = 11$  the system becomes singular.
- 15 The second pivot position will contain  $-2 - b$ . If  $b = -2$  we exchange with row 3. If  $b = -1$  (singular case) the second equation is  $-y - z = 0$ . A solution is  $(1, 1, -1)$ .
- Example of**
- $$\begin{array}{rcl} 0x + 0y + 2z & = & 4 \\ x + 2y + 2z & = & 5 \\ 0x + 3y + 4z & = & 6 \end{array}$$
- Exchange**
- $$\begin{array}{rcl} 0x + 3y + 4z & = & 4 \\ x + 2y + 2z & = & 5 \\ 0x + 3y + 4z & = & 6 \end{array}$$
- but then**
- break down**
- (exchange 1 and 2, then 2 and 3) (rows 1 and 3 are not consistent)
- 16 (a) 2 exchanges (b)
- 17 If row 1 = row 2, then row 2 is zero after the first step; exchange the zero row with row 3 and there is no *third* pivot. If column 2 = column 1, then column 2 has no pivot.
- 18 *Example*  $x + 2y + 3z = 0, 4x + 8y + 12z = 0, 5x + 10y + 15z = 0$  has 9 different coefficients but rows 2 and 3 become  $0 = 0$ : infinitely many solutions.
- 19 Row 2 becomes  $3y - 4z = 5$ , then row 3 becomes  $(q + 4)z = t - 5$ . If  $q = -4$  the system is singular—no third pivot. Then if  $t = 5$  the third equation is  $0 = 0$ . Choosing  $z = 1$  the equation  $3y - 4z = 5$  gives  $y = 3$  and equation 1 gives  $x = -9$ .
- 20 Singular if row 3 is a combination of rows 1 and 2. From the end view, the three planes form a triangle. This happens if rows  $1 + 2 =$  row 3 on the left side but not the right side:  $x + y + z = 0, x - 2y - z = 1, 2x - y = 4$ . No parallel planes but still no solution.
- 21 (a) Pivots  $2, \frac{3}{2}, \frac{4}{3}, \frac{5}{4}$  in the equations  $2x + y = 0, \frac{3}{2}y + z = 0, \frac{4}{3}z + t = 0, \frac{5}{4}t = 5$  after elimination. Back substitution gives  $t = 4, z = -3, y = 2, x = -1$ . (b) If the off-diagonal entries change from  $+1$  to  $-1$ , the pivots are the same. The solution is  $(1, 2, 3, 4)$  instead of  $(-1, 2, -3, 4)$ .
- 22 The fifth pivot is  $\frac{6}{5}$  for both matrices ( $1$ 's or  $-1$ 's off the diagonal). The  $n$ th pivot is  $\frac{n+1}{n}$ .

- 23** If ordinary elimination leads to  $x + y = 1$  and  $2y = 3$ , the original second equation could be  $2y + \ell(x + y) = 3 + \ell$  for any  $\ell$ . Then  $\ell$  will be the multiplier to reach  $2y = 3$ .
- 24** Elimination fails on  $\begin{bmatrix} a & 2 \\ a & a \end{bmatrix}$  if  $a = 2$  or  $a = 0$ .
- 25**  $a = 2$  (equal columns),  $a = 4$  (equal rows),  $a = 0$  (zero column).
- 26** Solvable for  $s = 10$  (add the two pairs of equations to get  $a + b + c + d$  on the left sides, 12 and  $2 + s$  on the right sides). The four equations for  $a, b, c, d$  are **singular**! Two solutions are  $\begin{bmatrix} 1 & 3 \\ 1 & 7 \end{bmatrix}$  and  $\begin{bmatrix} 0 & 4 \\ 2 & 6 \end{bmatrix}$ ,  $A = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix}$  and  $U = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ .
- 27** Elimination leaves the diagonal matrix  $\text{diag}(3, 2, 1)$  in  $3x = 3, 2y = 2, z = 4$ . Then  $x = 1, y = 1, z = 4$ .
- 28**  $A(2, :) = A(2, :) - 3 * A(1, :)$  subtracts 3 times row 1 from row 2.
- 29** The average pivots for  $\text{rand}(3)$  *without* row exchanges were  $\frac{1}{2}, 5, 10$  in one experiment—but pivots 2 and 3 can be arbitrarily large. Their averages are actually infinite! *With row exchanges* in MATLAB's  $\text{lu}$  code, the averages .75 and .50 and .365 are much more stable (and should be predictable, also for  $\text{randn}$  with normal instead of uniform probability distribution).
- 30** If  $A(5, 5)$  is 7 not 11, then the last pivot will be 0 not 4.
- 31** Row  $j$  of  $U$  is a combination of rows  $1, \dots, j$  of  $A$ . If  $A\mathbf{x} = \mathbf{0}$  then  $U\mathbf{x} = \mathbf{0}$  (not true if  $\mathbf{b}$  replaces  $\mathbf{0}$ ).  $U$  is the diagonal of  $A$  when  $A$  is *lower triangular*.
- 32** The question deals with 100 equations  $A\mathbf{x} = \mathbf{0}$  when  $A$  is singular.
- (a) Some linear combination of the 100 rows is **the row of 100 zeros**.
  - (b) Some linear combination of the 100 **columns** is **the column of zeros**.
  - (c) A very singular matrix has all ones:  $A = \text{eye}(100)$ . A better example has 99 random rows (or the numbers  $1^i, \dots, 100^i$  in those rows). The 100th row could be the sum of the first 99 rows (or any other combination of those rows with no zeros).
  - (d) The row picture has 100 planes **meeting along a common line through 0**. The column picture has 100 vectors all in the same 99-dimensional hyperplane.

### Problem Set 2.3, page 63

- 1**  $E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ ,  $E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 7 & 1 \end{bmatrix}$ ,  $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ .
- 2**  $E_{32}E_{21}\mathbf{b} = (1, -5, -35)$  but  $E_{21}E_{32}\mathbf{b} = (1, -5, 0)$ . When  $E_{32}$  comes first, row 3 feels no effect from row 1.
- 3**  $\begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$   $M = E_{32}E_{31}E_{21} = \begin{bmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 10 & -2 & 1 \end{bmatrix}$ .

**4** Elimination on column 4:  $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \xrightarrow{E_{21}} \begin{bmatrix} 1 \\ -4 \\ 0 \end{bmatrix} \xrightarrow{E_{31}} \begin{bmatrix} 1 \\ -4 \\ 2 \end{bmatrix} \xrightarrow{E_{32}} \begin{bmatrix} 1 \\ -4 \\ 10 \end{bmatrix}$ . The original  $A\mathbf{x} = \mathbf{b}$  has become  $U\mathbf{x} = \mathbf{c} = (1, -4, 10)$ . Then back substitution gives  $z = -5, y = \frac{1}{2}, x = \frac{1}{2}$ . This solves  $A\mathbf{x} = (1, 0, 0)$ .

**5** Changing  $a_{33}$  from 7 to 11 will change the third pivot from 5 to 9. Changing  $a_{33}$  from 7 to 2 will change the pivot from 5 to *no pivot*.

**6** Example:  $\begin{bmatrix} 2 & 3 & 7 \\ 2 & 3 & 7 \\ 2 & 3 & 7 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \\ 4 \end{bmatrix}$ . If all columns are multiples of column 1, there is no second pivot.

**7** To reverse  $E_{31}$ , **add** 7 times row 1 to row 3. The inverse of the elimination matrix

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -7 & 0 & 1 \end{bmatrix} \text{ is } E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 7 & 0 & 1 \end{bmatrix}.$$

**8**  $M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$  and  $M^* = \begin{bmatrix} a & b \\ c - \ell a & d - \ell b \end{bmatrix}$ .  $\det M^* = a(d - \ell b) - b(c - \ell a)$  reduces to  $ad - bc$ !

**9**  $M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix}$ . After the exchange, we need  $E_{31}$  (not  $E_{21}$ ) to act on the new row 3.

**10**  $E_{13} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}; \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}; E_{31}E_{13} = \begin{bmatrix} 2 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$ . Test on the identity matrix!

**11** An example with two negative pivots is  $A = \begin{bmatrix} 1 & 2 & 2 \\ 1 & 1 & 2 \\ 1 & 2 & 1 \end{bmatrix}$ . The diagonal entries can change sign during elimination.

**12** The first product is  $\begin{bmatrix} 9 & 8 & 7 \\ 6 & 5 & 4 \\ 3 & 2 & 1 \end{bmatrix}$  rows and also columns reversed. The second product is  $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 2 & -3 \end{bmatrix}$ .

**13** (a)  $E$  times the third column of  $B$  is the third column of  $EB$ . A column that starts at zero will stay at zero. (b)  $E$  could add row 2 to row 3 to change a zero row to a nonzero row.

**14**  $E_{21}$  has  $-\ell_{21} = \frac{1}{2}$ ,  $E_{32}$  has  $-\ell_{32} = \frac{2}{3}$ ,  $E_{43}$  has  $-\ell_{43} = \frac{3}{4}$ . Otherwise the  $E$ 's match  $I$ .

**15**  $a_{ij} = 2i - 3j$ :  $A = \begin{bmatrix} -1 & -4 & -7 \\ 1 & -2 & -5 \\ 3 & 0 & -3 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & -4 & -7 \\ 0 & -6 & -12 \\ 0 & -12 & -24 \end{bmatrix}$ . The zero became  $-12$ ,

an example of *fill-in*. To remove that  $-12$ , choose  $E_{32} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$ .

- 16** (a) The ages of  $X$  and  $Y$  are  $x$  and  $y$ :  $x - 2y = 0$  and  $x + y = 33$ ;  $x = 22$  and  $y = 11$  (b) The line  $y = mx + c$  contains  $x = 2, y = 5$  and  $x = 3, y = 7$  when  $2m + c = 5$  and  $3m + c = 7$ . Then  $m = 2$  is the slope.

- 17** The parabola  $y = a + bx + cx^2$  goes through the 3 given points when 
$$\begin{aligned} a + b + c &= 4 \\ a + 2b + 4c &= 8 \\ a + 3b + 9c &= 14 \end{aligned}$$
 Then  $a = 2, b = 1$ , and  $c = 1$ . This matrix with columns  $(1, 1, 1), (1, 2, 3), (1, 4, 9)$  is a "Vandermonde matrix."

**18**  $EF = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b & c & 1 \end{bmatrix}, FE = \begin{bmatrix} 1 & 0 & 0 \\ a & 1 & 0 \\ b+ac & c & 1 \end{bmatrix}, E^2 = \begin{bmatrix} 1 & 0 & 0 \\ 2a & 1 & 0 \\ 2b & 0 & 1 \end{bmatrix}, F^3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 3c & 1 \end{bmatrix}.$

**19**  $PQ = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ . In the opposite order, two row exchanges give  $QP = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix},$

If  $M$  exchanges rows 2 and 3 then  $M^2 = I$  (also  $(-M)^2 = I$ ). There are many square roots of  $I$ : Any matrix  $M = \begin{bmatrix} a & b \\ c & -a \end{bmatrix}$  has  $M^2 = I$  if  $a^2 + bc = 1$ .

- 20** (a) Each column of  $EB$  is  $E$  times a column of  $B$  (b)  $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 4 \\ 1 & 2 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$ . All rows of  $EB$  are *multiples* of  $\begin{bmatrix} 1 & 2 & 4 \end{bmatrix}$ .

**21** No.  $E = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$  and  $F = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  give  $EF = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$  but  $FE = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$ .

**22** (a)  $\sum a_{3j}x_j$  (b)  $a_{21} - a_{11}$  (c)  $a_{21} - 2a_{11}$  (d)  $(EA\mathbf{x})_1 = (A\mathbf{x})_1 = \sum a_{1j}x_j$ .

- 23**  $E(EA)$  subtracts 4 times row 1 from row 2 ( $EEA$  does the row operation twice).  $AE$  subtracts 2 times column 2 of  $A$  from column 1 (multiplication by  $E$  on the right side acts on **columns** instead of rows).

**24**  $\begin{bmatrix} A & b \end{bmatrix} = \begin{bmatrix} 2 & 3 & \mathbf{1} \\ 4 & 1 & \mathbf{17} \end{bmatrix} \rightarrow \begin{bmatrix} 2 & 3 & \mathbf{1} \\ 0 & -5 & \mathbf{15} \end{bmatrix}$ . The triangular system is  $\begin{aligned} 2x_1 + 3x_2 &= 1 \\ -5x_2 &= 15 \end{aligned}$   
Back substitution gives  $x_1 = 5$  and  $x_2 = -3$ .

- 25** The last equation becomes  $0 = 3$ . If the original 6 is 3, then row 1 + row 2 = row 3.

**26** (a) Add two columns  $\mathbf{b}$  and  $\mathbf{b}^*$   $\begin{bmatrix} 1 & 4 & 1 & 0 \\ 2 & 7 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 4 & 1 & 0 \\ 0 & -1 & -2 & 1 \end{bmatrix} \rightarrow \mathbf{x} = \begin{bmatrix} -7 \\ 2 \end{bmatrix}$   
and  $\mathbf{x}^* = \begin{bmatrix} 4 \\ -1 \end{bmatrix}$ .

- 27** (a) No solution if  $d = 0$  and  $c \neq 0$  (b) Many solutions if  $d = 0 = c$ . No effect from  $a, b$ .

**28**  $A = AI = A(BC) = (AB)C = IC = C$ . That middle equation is crucial.

29  $E = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 \end{bmatrix}$  subtracts each row from the next row. The result  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix}$  still has multipliers = 1 in a 3 by 3 Pascal matrix. The product  $M$  of all elimination matrices is  $\begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix}$ . This “alternating sign Pascal matrix” is on page 88.

30 Given positive integers with  $ad - bc = 1$ . Certainly  $c < a$  and  $b < d$  would be impossible. Also  $c > a$  and  $b > d$  would be impossible with integers. This leaves row 1 < row 2 OR row 2 < row 1. An example is  $M = \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix}$ . Multiply by  $\begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$  to get  $\begin{bmatrix} 1 & 1 \\ 2 & 3 \end{bmatrix}$ , then multiply twice by  $\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$  to get  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ . This shows that  $M = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ .

$$31 \quad E_{21} = \begin{bmatrix} 1 & & & \\ 1/2 & 1 & & \\ 0 & 0 & 1 & \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad E_{32} = \begin{bmatrix} 1 & & & \\ 0 & 1 & & \\ 0 & 2/3 & 1 & \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad E_{43} = \begin{bmatrix} 1 & & & \\ 0 & 1 & & \\ 0 & 0 & 1 & \\ 0 & 0 & 3/4 & 1 \end{bmatrix},$$

$$E_{43} E_{32} E_{21} = \begin{bmatrix} 1 & & & \\ 1/2 & 1 & & \\ 1/3 & 2/3 & 1 & \\ 1/4 & 2/4 & 3/4 & 1 \end{bmatrix}$$

### Problem Set 2.4, page 75

- 1 If all entries of  $A, B, C, D$  are 1, then  $BA = 3 \text{ ones}(5)$  is 5 by 5;  $AB = 5 \text{ ones}(3)$  is 3 by 3;  $ABD = 15 \text{ ones}(3, 1)$  is 3 by 1.  $DBA$  and  $A(B + C)$  are not defined.
- 2 (a)  $A$  (column 3 of  $B$ )      (b) (Row 1 of  $A$ )  $B$       (c) (Row 3 of  $A$ )(column 4 of  $B$ )  
(d) (Row 1 of  $C$ ) $D$ (column 1 of  $E$ ).
- 3  $AB + AC$  is the same as  $A(B + C) = \begin{bmatrix} 3 & 8 \\ 6 & 9 \end{bmatrix}$ . (*Distributive law*).
- 4  $A(BC) = (AB)C$  by the *associative law*. In this example both answers are  $\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$  from column 1 of  $AB$  and row 2 of  $C$  (multiply columns times rows).
- 5 (a)  $A^2 = \begin{bmatrix} 1 & 2b \\ 0 & 1 \end{bmatrix}$  and  $A^n = \begin{bmatrix} 1 & nb \\ 0 & 1 \end{bmatrix}$ .      (b)  $A^2 = \begin{bmatrix} 4 & 4 \\ 0 & 0 \end{bmatrix}$  and  $A^n = \begin{bmatrix} 2^n & 2^n \\ 0 & 0 \end{bmatrix}$ .
- 6  $(A + B)^2 = \begin{bmatrix} 10 & 4 \\ 6 & 6 \end{bmatrix} = A^2 + AB + BA + B^2$ . But  $A^2 + 2AB + B^2 = \begin{bmatrix} 16 & 2 \\ 3 & 0 \end{bmatrix}$ .
- 7 (a) True      (b) False      (c) True      (d) False: usually  $(AB)^2 \neq A^2B^2$ .

- 8 The rows of  $DA$  are 3 (row 1 of  $A$ ) and 5 (row 2 of  $A$ ). Both rows of  $EA$  are row 2 of  $A$ . The columns of  $AD$  are 3 (column 1 of  $A$ ) and 5 (column 2 of  $A$ ). The first column of  $AE$  is zero, the second is column 1 of  $A$  + column 2 of  $A$ .
- 9  $AF = \begin{bmatrix} a & a+b \\ c & c+d \end{bmatrix}$  and  $E(AF)$  equals  $(EA)F$  because matrix multiplication is associative.
- 10  $FA = \begin{bmatrix} a+c & b+d \\ c & d \end{bmatrix}$  and then  $E(FA) = \begin{bmatrix} a+c & b+d \\ a+2c & b+2d \end{bmatrix}$ .  $E(FA)$  is not the same as  $F(EA)$  because multiplication is not commutative.
- 11 (a)  $B = 4I$  (b)  $B = 0$  (c)  $B = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix}$  (d) Every row of  $B$  is 1, 0, 0.
- 12  $AB = \begin{bmatrix} a & 0 \\ c & 0 \end{bmatrix} = BA = \begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix}$  gives  $b = c = 0$ . Then  $AC = CA$  gives  $a = d$ . The only matrices that commute with  $B$  and  $C$  (and all other matrices) are multiples of  $I$ :  $A = aI$ .
- 13  $(A - B)^2 = (B - A)^2 = A(A - B) - B(A - B) = A^2 - AB - BA + B^2$ . In a typical case (when  $AB \neq BA$ ) the matrix  $A^2 - 2AB + B^2$  is different from  $(A - B)^2$ .
- 14 (a) True ( $A^2$  is only defined when  $A$  is square) (b) False (if  $A$  is  $m$  by  $n$  and  $B$  is  $n$  by  $m$ , then  $AB$  is  $m$  by  $m$  and  $BA$  is  $n$  by  $n$ ). (c) True (d) False (take  $B = 0$ ).
- 15 (a)  $mn$  (use every entry of  $A$ ) (b)  $mnp = p \times \text{part (a)}$  (c)  $n^3$  ( $n^2$  dot products).
- 16 (a) Use only column 2 of  $B$  (b) Use only row 2 of  $A$  (c)–(d) Use row 2 of first  $A$ .
- 17  $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3 \end{bmatrix}$  has  $a_{ij} = \min(i, j)$ .  $A = \begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & -1 \\ 1 & -1 & 1 \end{bmatrix}$  has  $a_{ij} = (-1)^{i+j} =$   
 “alternating sign matrix”.  $A = \begin{bmatrix} 1/1 & 1/2 & 1/3 \\ 2/1 & 2/2 & 2/3 \\ 3/1 & 3/2 & 3/3 \end{bmatrix}$  has  $a_{ij} = i/j$  (this will be an example of a *rank one matrix*).
- 18 Diagonal matrix, lower triangular, symmetric, all rows equal. Zero matrix fits all four.
- 19 (a)  $a_{11}$  (b)  $\ell_{31} = a_{31}/a_{11}$  (c)  $a_{32} - (\frac{a_{31}}{a_{11}})a_{12}$  (d)  $a_{22} - (\frac{a_{21}}{a_{11}})a_{12}$ .
- 20  $A^2 = \begin{bmatrix} 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ ,  $A^3 = \begin{bmatrix} 0 & 0 & 0 & 8 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ ,  $A^4 =$  zero matrix for *strictly triangular*  $A$ .  
 Then  $A\mathbf{v} = A \begin{bmatrix} x \\ y \\ z \\ t \end{bmatrix} = \begin{bmatrix} 2y \\ 2z \\ 2t \\ 0 \end{bmatrix}$ ,  $A^2\mathbf{v} = \begin{bmatrix} 4z \\ 4t \\ 0 \\ 0 \end{bmatrix}$ ,  $A^3\mathbf{v} = \begin{bmatrix} 8t \\ 0 \\ 0 \\ 0 \end{bmatrix}$ ,  $A^4\mathbf{v} = 0$ .